# Geodesics in curved spacetime 

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Geodesics can be defined either as extremal curves with the shortest possible path length or as the curves that depart as little as possible from straightness (they are "locally straight").

## 1 The geodesic equation - 1

Here, we obtain the geodesic equation looking at geodesics as the trajectories that depart as little as possible from straightness. A point mass moving along a geodesic has its velocity vector $U=d X / d \tau$ always tangent to the path. A geodesic is "locally straight", therefore we require that the velocity vector does not change locally, i.e., that the absolute derivative vanishes

$$
\begin{equation*}
0=\frac{d U}{d \tau}=\frac{d}{d \tau}\left(U^{\mu} \varepsilon_{\mu}\right)=\frac{d U^{\mu}}{d \tau} \varepsilon_{\mu}+U^{\mu} \frac{d \varepsilon_{\mu}}{d \tau} \tag{1}
\end{equation*}
$$

Since

$$
\begin{equation*}
\frac{d \varepsilon_{\mu}}{d \tau}=\frac{\partial \varepsilon_{\mu}}{\partial x^{\nu}} \frac{d x^{\nu}}{d \tau}=U^{\nu} \Gamma_{\mu \nu}^{\sigma} \varepsilon_{\sigma} \tag{2}
\end{equation*}
$$

we find

$$
\begin{equation*}
\frac{d^{2} x^{\mu}}{d \tau} \varepsilon_{\mu}+\frac{d x^{\mu}}{d \tau} \frac{d x^{\nu}}{d \tau} \Gamma_{\mu \nu}^{\sigma} \varepsilon_{\sigma}=0 \tag{3}
\end{equation*}
$$

and finally, exchanging $\sigma$ and $\mu$

$$
\begin{equation*}
\frac{d^{2} x^{\mu}}{d \tau}+\frac{d x^{\sigma}}{d \tau} \frac{d x^{\nu}}{d \tau} \Gamma_{\sigma \nu}^{\mu}=0 \tag{4}
\end{equation*}
$$

which is the geodesic equation.
The second term in the geodesic equation contains the basic information about curvature: we see as the connection coefficients approach zero, and therefore we are close to a flat spacetime, the solution of the geodesic equation approaches a straight line in spacetime, which is the solution in SR.

## 2 The geodesic equation - 2

Here, we obtain the geodesic equation from the principle of least action applied to a free particle (freely falling along a geodesic).

### 2.1 Free-particle Lagrangian

The action must be a scalar invariant, and the only such scalar for a free particle is

$$
\begin{equation*}
S=-\alpha \int_{a}^{b} d s \tag{5}
\end{equation*}
$$

where $a, b$ are the initial and final position of the particle in spacetime, and $\alpha$ is a constant pertaining to the particle under study.

In the rest system of the particle, the spacetime interval is proportional to the proper time interval $d s=c d \tau$. If $d t^{\prime}$ is the time interval in the reference frame of the observer, then we can write the spacetime interval in both systems as follows

$$
\begin{equation*}
d s^{2}=c^{2} d t^{2}-\left(d x^{2}+d y^{2}+d z^{2}\right)=c^{2} d \tau^{2} \tag{6}
\end{equation*}
$$

where ( $x, y, z$ ) denotes the position of the particle in the observer's reference frame, therefore

$$
\begin{equation*}
d t=\gamma d \tau \geq d \tau \tag{7}
\end{equation*}
$$

Writing the action in terms of Lagrangian, we find an equivalent expression for the integral in the observer's reference frame

$$
\begin{equation*}
S=-\alpha \int_{t_{1}}^{t_{2}} d s=-\alpha \int_{t_{1}}^{t_{2}} c d \tau=-\alpha \int_{t_{1}}^{t_{2}} c \sqrt{1-\beta^{2}} d t=\int_{t_{1}}^{t_{2}} L d t \tag{8}
\end{equation*}
$$

Expanding the square root at low $\beta$ and using the Lagrangian for the free particle in Newtonian mechanics $L=m v^{2} / 2$, we find that the last equality becomes

$$
\begin{equation*}
-\alpha c\left(1-\frac{1}{2} \beta^{2}\right) \sim \frac{1}{2} m v^{2} \tag{9}
\end{equation*}
$$

and dropping the constant which is nonrelevant in setting up the Lagrange equations, we find

$$
\begin{equation*}
\alpha \frac{v^{2}}{2 c}=\frac{1}{2} m v^{2} \tag{10}
\end{equation*}
$$

which shows that, in order to have agreement between the relativistic expression and the classical expression, we must have $\alpha=m c$, and that the expression for the action of the free particle is

$$
\begin{equation*}
S=-m c \int_{a}^{b} \sqrt{g_{\mu \nu} d x^{\mu} d x^{\nu}} \tag{11}
\end{equation*}
$$

### 2.2 The geodesic equation from the Euler-Lagrange equations

Recall that, given a Lagrangian function $L\left(q_{i}, \dot{q}_{i}\right)$, the equations of motion can be obtained from the Euler-Lagrange equations

$$
\begin{equation*}
\frac{d}{d t}\left(\frac{\partial L}{\partial \dot{q}_{i}}\right)-\frac{\partial L}{\partial q_{i}}=0 \tag{12}
\end{equation*}
$$

In this case we work with a reduced Lagrangian, where we drop the multiplicative constants that play no role in the Lagrange equations

$$
\begin{equation*}
L\left(x^{\alpha}, \dot{x}^{\alpha}\right)=\sqrt{g_{\mu \nu} \frac{d x^{\mu}}{d \sigma} \frac{d x^{\nu}}{d \sigma}}=\frac{d \tau}{d \sigma} \tag{13}
\end{equation*}
$$

which is calculated along a trajectory parameterized by the scalar parameter $\sigma$, where the derivatives are computed with respect to this parameter, $\dot{x}^{\mu}=d x^{\mu} / d \sigma$ and

$$
\begin{equation*}
\frac{d}{d \sigma}\left(\frac{\partial L}{\partial \dot{x}^{\alpha}}\right)-\frac{\partial L}{d x^{\alpha}}=0 \tag{14}
\end{equation*}
$$

In 4-dimensional space this corresponds to 4 equations in all.
The metric tensor changes along the curve, it only depends on $x^{\mu}$ and is not dependent on $\dot{x}^{\mu}$. Therefore

$$
\begin{equation*}
\frac{\partial L}{\partial \dot{x}^{\alpha}}=\frac{1}{2 \sqrt{g_{\mu \nu} \dot{x}^{\mu} \dot{x}^{\nu}}}\left(g_{\mu \nu} \delta_{\alpha}^{\mu} \dot{x}^{\nu}+g_{\mu \nu} \dot{x}^{\mu} \delta_{\alpha}^{\nu}\right)=\frac{1}{2 L}\left(g_{\alpha \nu} \dot{x}^{\nu}+g_{\mu \alpha} \dot{x}^{\mu}\right)=\frac{1}{L} g_{\alpha \mu} \frac{d x^{\mu}}{d \sigma}=g_{\alpha \mu} \frac{d x^{\mu}}{d \tau} \tag{15}
\end{equation*}
$$

Similarly, we find

$$
\begin{equation*}
\frac{\partial L}{\partial x^{\alpha}}=\frac{1}{2 L} \partial_{\alpha} g_{\mu \nu} \frac{d x^{\mu}}{d \sigma} \frac{d x^{\nu}}{d \sigma}=\frac{1}{2} \partial_{\alpha} g_{\mu \nu} \frac{d x^{\mu}}{d \sigma} \frac{d x^{\nu}}{d \tau} . \tag{16}
\end{equation*}
$$

Plugging these results in the Euler-Lagrange equations, we obtain

$$
\begin{equation*}
\frac{d}{d \sigma}\left(g_{\alpha \mu} \frac{d x^{\mu}}{d \tau}\right)-\frac{1}{2} \partial_{\alpha} g_{\mu \nu} \frac{d x^{\mu}}{d \sigma} \frac{d x^{\nu}}{d \tau}=0 \tag{17}
\end{equation*}
$$

and after multiplying times $d \sigma / d \tau$

$$
\begin{equation*}
\frac{d}{d \tau}\left(g_{\alpha \mu} \frac{d x^{\mu}}{d \tau}\right)-\frac{1}{2} \partial_{\alpha} g_{\mu \nu} \frac{d x^{\mu}}{d \tau} \frac{d x^{\nu}}{d \tau}=0 \tag{18}
\end{equation*}
$$

which is the geodesic equation obtained from the Lagrangian formulation.

## 3 Equivalence of the two geodesic equations

We have found two apparently different geodesic equations; those found with the method of parallel transport of the tangent vector are

$$
\begin{equation*}
\frac{d^{2} x^{\alpha}}{d \tau^{2}}+\Gamma_{\mu \nu}^{\alpha} \dot{x}^{\mu} \dot{x}^{\nu}=0 \tag{19}
\end{equation*}
$$

and the geodesic equations obtained from the relativistic Lagrangian of a free particle are

$$
\begin{equation*}
\frac{d}{d \tau}\left(g_{\alpha \mu} \frac{d x^{\mu}}{d \tau}\right)-\frac{1}{2} \partial_{\alpha} g_{\mu \nu} \dot{x}^{\mu} \dot{x}^{\nu}=0 \tag{20}
\end{equation*}
$$

In this section we show that they are equivalent.
Notice first that

$$
\begin{align*}
\frac{d}{d \tau}\left(g_{\alpha \mu} \frac{d x^{\mu}}{d \tau}\right) & =\frac{d g_{\alpha \mu}}{d \tau} \frac{d x^{\mu}}{d \tau}+g_{\alpha \mu} \frac{d x^{\mu}}{d \tau}  \tag{21}\\
& =\partial_{\nu} g_{\alpha \mu} \dot{x}^{\mu} \dot{x}^{\nu}+g_{\alpha \mu} \frac{d^{2} x^{\mu}}{d \tau^{2}} \tag{22}
\end{align*}
$$

therefore

$$
\begin{equation*}
\partial_{\nu} g_{\alpha \mu} \dot{x}^{\mu} \dot{x}^{\nu}+g_{\alpha \mu} \frac{d^{2} x^{\mu}}{d \tau^{2}}-\frac{1}{2} \partial_{\alpha} g_{\mu \nu} \dot{x}^{\mu} \dot{x}^{\nu}=0 \tag{23}
\end{equation*}
$$

Next, we exchange $\mu$ and $\alpha$

$$
\begin{equation*}
\partial_{\nu} g_{\alpha \mu} \dot{x}^{\alpha} \dot{x}^{\nu}+g_{\alpha \mu} \frac{d^{2} x^{\alpha}}{d \tau^{2}}-\frac{1}{2} \partial_{\mu} g_{\alpha \nu} \dot{x}^{\alpha} \dot{x}^{\nu}=0 \tag{24}
\end{equation*}
$$

rearrange the equation

$$
\begin{equation*}
\frac{d^{2} x^{\beta}}{d \tau^{2}}+\frac{1}{2} g^{\beta \mu}\left(\partial_{\nu} g_{\alpha \mu}+\partial_{\nu} g_{\alpha \mu}-\partial_{\mu} g_{\alpha \nu}\right) \dot{x}^{\alpha} \dot{x}^{\nu}=0 \tag{25}
\end{equation*}
$$

exchange $\beta$ and $\alpha$

$$
\begin{equation*}
\frac{d^{2} x^{\alpha}}{d \tau^{2}}+\frac{1}{2} g^{\alpha \mu}\left(\partial_{\nu} g_{\beta \mu}+\partial_{\nu} g_{\beta \mu}-\partial_{\mu} g_{\beta \nu}\right) \dot{x}^{\beta} \dot{x}^{\nu}=0 \tag{26}
\end{equation*}
$$

and finally, $\beta$ and $\mu$

$$
\begin{equation*}
\frac{d^{2} x^{\alpha}}{d \tau^{2}}+\frac{1}{2} g^{\alpha \beta}\left(\partial_{\nu} g_{\beta \mu}+\partial_{\nu} g_{\beta \mu}-\partial_{\beta} g_{\mu \nu}\right) \dot{x}^{\mu} \dot{x}^{\nu}=0 \tag{27}
\end{equation*}
$$

Expanding the parenthesis, the second term is $\partial_{\nu} g_{\beta \mu} \dot{x}^{\mu} \dot{x}^{\nu}=\partial_{\mu} g_{\beta \nu} \dot{x}^{\mu} \dot{x}^{\nu}$ (exchanging $\mu$ and $\nu$ ), and therefore

$$
\begin{equation*}
\frac{d^{2} x^{\alpha}}{d \tau^{2}}+\frac{1}{2} g^{\alpha \beta}\left(\partial_{\nu} g_{\beta \mu}+\partial_{\mu} g_{\beta \nu}-\partial_{\beta} g_{\mu \nu}\right) \dot{x}^{\mu} \dot{x}^{\nu}=0 \tag{28}
\end{equation*}
$$

and recalling that

$$
\Gamma_{j k}^{i}=\frac{1}{2} g^{i \ell}\left(\frac{\partial g_{\ell k}}{\partial x^{j}}+\frac{\partial g_{\ell j}}{\partial x^{k}}-\frac{\partial g_{j k}}{\partial x^{\ell}}\right)
$$

we find the first version of the geodesic equation

$$
\begin{equation*}
\frac{d^{2} x^{\alpha}}{d \tau^{2}}+\frac{1}{2} \Gamma_{\mu \nu}^{\alpha} \dot{x}^{\mu} \dot{x}^{\nu}=0 \tag{29}
\end{equation*}
$$

and conclude the proof of the equivalence.

