

# The Riemann tensor

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## 1 Introduction

We transport a vector by keeping it parallel as we move from one point to a close one on a manifold. Parallel transport in flat space is trivial, as we do it following a closed loop, the transported vector overlaps the initial one when we close the loop (left panel of Fig. 1). The situation is much less trivial on a manifold with curvature, the right panel of Fig. 1 illustrates what happens on the surface of a sphere, we see that the transported vector no longer overlaps the initial one. Moreover, in curved space the final result depends on the path taken. This last remark has a stunning consequence, that in a curved spacetime we cannot really “compare velocities” at different spacetime points, because a comparison means that one of the two vectors must be “parallel transported” to the other one and this depends on the path.

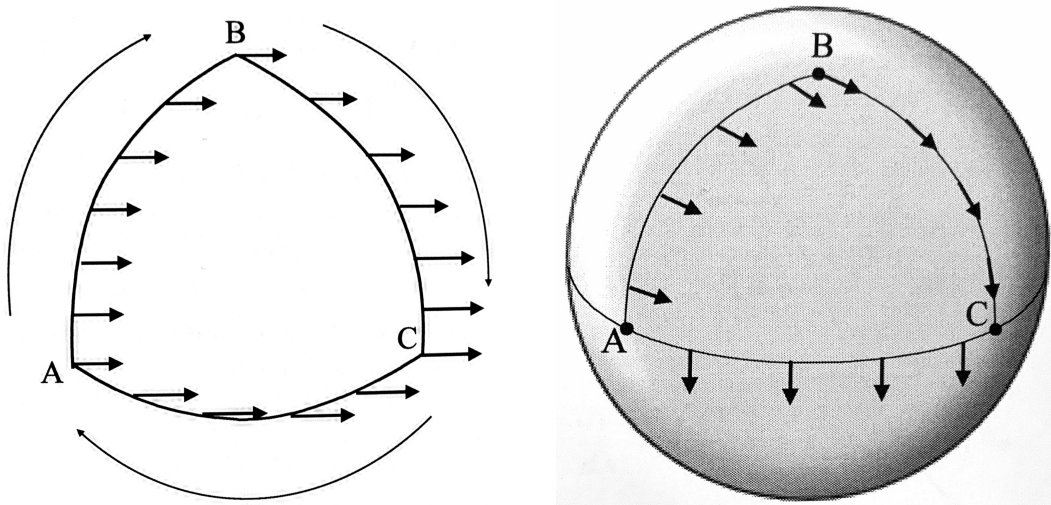


Figure 1: Left panel: parallel transport of a vector along a closed loop in flat space. Right panel: parallel transport of a vector along a closed loop on a sphere.

Parallel transport is closely connected to the curvature of a Riemann manifold. In this handout we explore these concepts.

## 2 Equation of parallel transport

Parallel transport generalizes to curved space the idea that we keep a vector constant as we move along a path  $x^\mu(\sigma)$ . For a generic tensor in flat space this means

$$\frac{d}{d\sigma} T_{\nu_1, \dots, \nu_\ell}^{\mu_1, \dots, \mu_k} = \frac{dx^\mu}{d\sigma} \frac{\partial}{\partial x^\mu} T_{\nu_1, \dots, \nu_\ell}^{\mu_1, \dots, \mu_k} = 0 \quad (1)$$

and we generalize the idea to curved spaces by replacing the partial derivative with the **directional covariant derivative**

$$\frac{D}{d\sigma} = \frac{dx^\mu}{d\sigma} \nabla_\mu \quad (2)$$

so that the equation of parallel transport of a tensor becomes

$$\frac{D}{d\sigma} T_{\nu_1, \dots, \nu_\ell}^{\mu_1, \dots, \mu_k} = \frac{dx^\mu}{d\sigma} \nabla_\mu T_{\nu_1, \dots, \nu_\ell}^{\mu_1, \dots, \mu_k} = 0 \quad (3)$$

In the case of a contravariant vector, the equation becomes

$$\frac{dx^\mu}{d\sigma} \nabla_\mu V^\alpha = \frac{dx^\mu}{d\sigma} \left( \frac{\partial V^\alpha}{\partial x^\mu} + \Gamma_{\mu\beta}^\alpha V^\beta \right) = \frac{dV^\alpha}{d\sigma} + \Gamma_{\mu\beta}^\alpha \frac{dx^\mu}{d\sigma} V^\beta = 0 \quad (4)$$

### 2.1 Parallel transport of the metric tensor

The metric tensor always satisfies the parallel transport equation. This can be seen as follows:

$$\begin{aligned} \nabla_\sigma g_{\mu\nu} &= \partial_\sigma g_{\mu\nu} - g_{\lambda\nu} \Gamma_{\mu\sigma}^\lambda - g_{\mu\lambda} \Gamma_{\sigma\nu}^\lambda \\ &= \partial_\sigma g_{\mu\nu} - g_{\lambda\nu} \frac{1}{2} g^{\lambda\alpha} (\partial_\mu g_{\alpha\sigma} + \partial_\sigma g_{\mu\alpha} - \partial_\alpha g_{\mu\sigma}) - g_{\mu\lambda} \frac{1}{2} g^{\lambda\alpha} (\partial_\nu g_{\alpha\sigma} + \partial_\sigma g_{\alpha\nu} - \partial_\alpha g_{\sigma\nu}) \\ &= \partial_\sigma g_{\mu\nu} - \frac{1}{2} \delta_\nu^\alpha (\partial_\mu g_{\alpha\sigma} + \partial_\sigma g_{\mu\alpha} - \partial_\alpha g_{\mu\sigma}) - \frac{1}{2} \delta_\mu^\alpha (\partial_\nu g_{\alpha\sigma} + \partial_\sigma g_{\alpha\nu} - \partial_\alpha g_{\sigma\nu}) \\ &= \partial_\sigma g_{\mu\nu} - \frac{1}{2} (\partial_\mu g_{\nu\sigma} + \partial_\sigma g_{\mu\nu} - \partial_\nu g_{\mu\sigma}) - \frac{1}{2} (\partial_\nu g_{\mu\sigma} + \partial_\sigma g_{\mu\nu} - \partial_\mu g_{\sigma\nu}) \\ &= 0 \end{aligned} \quad (5)$$

This means that

$$\frac{D}{d\sigma} g_{\alpha\beta} = \frac{dx^\mu}{d\sigma} \nabla_\mu g_{\alpha\beta} = 0 \quad (6)$$

and **the metric tensor always satisfies the parallel transport equation.**

## 2.2 Parallel transport of the inner product of two parallel-transported vectors

The inner product of two contravariant parallel-transported vectors is defined by  $g_{\mu\nu}A^\mu B^\nu$ , therefore

$$\frac{D}{d\sigma}(g_{\mu\nu}A^\mu B^\nu) = \left(\frac{D}{d\sigma}g_{\mu\nu}\right)A^\mu B^\nu + g_{\mu\nu}\left(\frac{D}{d\sigma}A^\mu\right)B^\nu + g_{\mu\nu}A^\mu\left(\frac{D}{d\sigma}B^\nu\right) = 0 \quad (7)$$

because each term vanishes. This means that **parallel transport conserves the norm of parallel-transported vectors, their orthogonality, etc.**

## 2.3 The geodesic equation as a consequence of parallel transport

The tangent vector to the path  $x^\mu(\sigma)$  is  $dx^\mu/d\sigma$ , therefore the equation for parallel transport is just

$$\frac{d^2x^\alpha}{d\sigma^2} + \Gamma_{\mu\beta}^\alpha \frac{dx^\mu}{d\sigma} \frac{dx^\beta}{d\sigma} = 0 \quad (8)$$

which is the geodesic equation.

## 2.4 The local flatness theorem

Consider a transformation to primed coordinates that transforms the metric tensor as follows

$$g'_{\mu\nu} = \frac{\partial x^\alpha}{\partial x'^\mu} \frac{\partial x^\beta}{\partial x'^\nu} g_{\alpha\beta}, \quad (9)$$

here we prove that it is possible to find a transformation such that  $g'_{\mu\nu} = \eta_{\mu\nu}$  and  $\partial'_\alpha g'_{\mu\nu} = 0$ .

We start by series expanding the 16 elements of the Jacobian matrix at a spacetime point  $P$ , relative to the primed coordinates

$$\frac{\partial x^\alpha}{\partial x'^\mu} \approx a_\mu^\alpha + b_{\mu\lambda}^\alpha \Delta x'^\lambda + c_{\mu\lambda\sigma}^\alpha \Delta x'^\lambda \Delta x'^\sigma \quad (10)$$

where

$$\Delta x'^\mu = x'^\mu - [x'^\mu]_P \quad (11)$$

$$a_\mu^\alpha = \left[ \frac{\partial x^\alpha}{\partial x'^\mu} \right]_P \quad (12)$$

$$b_{\mu\lambda}^\alpha = \left[ \frac{\partial}{\partial x'^\lambda} \left( \frac{\partial x^\alpha}{\partial x'^\mu} \right) \right]_P = \left[ \frac{\partial^2 x^\alpha}{\partial x'^\lambda \partial x'^\mu} \right]_P \quad (13)$$

$$c_{\mu\lambda\sigma}^\alpha = \frac{1}{2} \left[ \frac{\partial^2}{\partial x'^\lambda \partial x'^\sigma} \left( \frac{\partial x^\alpha}{\partial x'^\mu} \right) \right]_P = \frac{1}{2} \left[ \frac{\partial^3 x^\alpha}{\partial x'^\lambda \partial x'^\sigma \partial x'^\mu} \right]_P \quad (14)$$

The choice of the coordinate transformation is free, and therefore we are free to choose the  $a$ ,  $b$  and  $c$  coefficients: we choose them in such a way that  $g'_{\mu\nu} = \eta_{\mu\nu}$  and  $\partial'_\alpha g'_{\mu\nu} = 0$ .

To start with, we count the number of independent values for each set of coefficients:

- there are no symmetries in the indexes of the  $a_\mu^\alpha$ s, therefore here we have 16 independent values,
- the  $b_{\mu\lambda}^\alpha$ s have an obvious exchange symmetry between the covariant indexes. This means that there are 40 independent values,
- again, the  $c_{\mu\lambda\sigma}^\alpha$ s have 80 distinct combination of indexes.

Next, we expand  $g_{\alpha\beta}$  in the primed coordinate system

$$g_{\alpha\beta} = [g_{\alpha\beta}]_P + [\partial'_\gamma g_{\alpha\beta}]_P \Delta x'^\gamma + \frac{1}{2} [\partial'_\gamma \partial'_\delta g_{\alpha\beta}]_P \Delta x'^\gamma \Delta x'^\delta \quad (15)$$

This means that we can write

$$\begin{aligned} g'_{\mu\nu} &\approx \left( a_\mu^\alpha + b_{\mu\lambda_1}^\alpha \Delta x'^{\lambda_1} + c_{\mu\lambda_1\sigma_1}^\alpha \Delta x'^{\lambda_1} \Delta x'^{\sigma_1} \right) \\ &\quad \times \left( a_\nu^\beta + b_{\nu\lambda_2}^\beta \Delta x'^{\lambda_2} + c_{\nu\lambda_2\sigma_2}^\beta \Delta x'^{\lambda_2} \Delta x'^{\sigma_2} \right) \\ &\quad \times \left( [g_{\alpha\beta}]_P + [\partial'_\gamma g_{\alpha\beta}]_P \Delta x'^\gamma + \frac{1}{2} [\partial'_\gamma \partial'_\delta g_{\alpha\beta}]_P \Delta x'^\gamma \Delta x'^\delta \right) \\ &\approx a_\mu^\alpha a_\nu^\beta [g_{\alpha\beta}]_P + \left( a_\nu^\beta b_{\mu\gamma}^\alpha [g_{\alpha\beta}]_P + a_\mu^\alpha b_{\nu\gamma}^\beta [g_{\alpha\beta}]_P + a_\mu^\alpha a_\nu^\beta [\partial'_\gamma g_{\alpha\beta}]_P \right) \Delta x'^\gamma \\ &\quad + \left( a_\mu^\alpha c_{\nu\gamma\delta}^\beta [g_{\alpha\beta}]_P + a_\nu^\beta c_{\mu\gamma\delta}^\alpha [g_{\alpha\beta}]_P + \text{terms with } a \text{ and } b \text{ only} \right) \Delta x'^\gamma \Delta x'^\delta \quad (16) \end{aligned}$$

Now consider the first term in the r.h.s. of Eq. (16); it depends on  $a$  alone, and it determines the value of  $g'_{\mu\nu}$  at the spacetime point P. Since  $g'_{\mu\nu}$  has only 10 independent elements, we see that the degrees of freedom carried by  $a$  are more than enough to let us choose  $a$  in such a way that  $[g'_{\mu\nu}]_P = \eta_{\mu\nu}$ . The 6 remaining degrees of freedom can be used for local rotations and Lorentz boosts.

The next question is, is this flatness stable enough to guarantee that in a neighbourhood of P the metric tensor does not change much and we can effectively say that this neighbourhood is locally flat? The  $\Delta x'^\gamma$ -dependent term can be tuned with the  $b$  coefficients, and it should yield the  $[\partial'_\gamma g'_{\alpha\beta}]_P$  term in the expansion of  $g'_{\alpha\beta}$ . Since this term corresponds to 40 independent coefficients, we have just enough freedom in the choice of coefficients to guarantee that we can set  $[\partial'_\gamma g'_{\alpha\beta}]_P = 0$ . **This means that we can choose coordinates such that the coordinate frame appears as locally flat in a small neighbourhood, i.e., a Local Inertially Frame (LIF).**

Can we play the same trick with local curvature (represented by the next term, dependent on  $\Delta x'^\gamma \Delta x'^\delta$ )? At this point we have exhausted the degrees of freedom

provided by  $a$  and  $b$  and we are left with just  $c$  (80 degrees of freedom). This is used to determine the next term in the expansion of  $g'_{\mu\nu}$ , which corresponds to 100 degrees of freedom, and we see that now we do not have enough freedom to choose a coordinate system that leads to a local vanishing of curvature.

**Finally, we find that the existence of the LIF is fully compatible with the earlier equality (5), which is also related with the symmetry of the Christoffel symbols: these results are all strictly interrelated.**

### 3 The Riemann tensor

In the first section we noticed that curvature produces a mismatch in the parallel transport of a vector around a loop. Clearly, to characterize local curvature, we should consider small, infinitesimal loops. Moreover, it is not strictly necessary to get back at

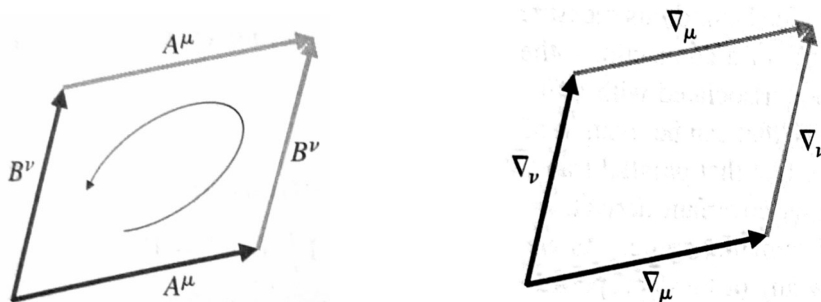


Figure 2: Left panel: a small loop defined by two (small) vectors  $A$  and  $B$ . Right panel: operators associated with parallel transport along the loop sides.

the origin of the loop, we could also move along “parallelogram edges” like those in the left panel of figure 2: the parallelogram is equivalent to a loop, but it lets us clearly display the difference between apparently equivalent paths to reach the same endpoint. We write this difference as follows

$$\delta V^\rho = R^\rho_{\sigma\mu\nu} V^\sigma A^\mu B^\nu \quad (17)$$

because in a small loop we expect the difference to be proportional to the vector size, and to the distance over which we transport the vector (i.e., along  $A$  and  $B$ ). The set of proportionality constants  $R^\rho_{\sigma\mu\nu}$  also depend on the directions of these vectors. Because of the quotient rule,  $R^\rho_{\sigma\mu\nu}$  is itself a tensor, known as the **Riemann tensor**. Changing the direction of the loop, the difference must change sign, therefore  $R^\rho_{\sigma\mu\nu}$  must be antisymmetric with respect to  $\mu$  and  $\nu$ .

More specifically, from the discussion in the previous section, we see that the covariant derivative is the proper operator to characterize differences in the parallel transport

of a vector any given direction on the manifold, and the order with which we take parallel transport defines a commutator (left panel in figure 2). Here, we expand the commutator

$$[\nabla_\mu, \nabla_\nu]V^\rho = \nabla_\mu \nabla_\nu V^\rho - \nabla_\nu \nabla_\mu V^\rho \quad (18)$$

$$= \partial_\mu(\nabla_\nu V^\rho) + \Gamma_{\mu\lambda}^\rho \nabla_\nu V^\lambda - \Gamma_{\mu\nu}^\sigma \nabla_\sigma V^\rho - (\mu \leftrightarrow \nu) \quad (19)$$

$$= \partial_\mu(\partial_\nu V^\rho + \Gamma_{\nu\lambda}^\rho V^\lambda) + \Gamma_{\mu\lambda}^\rho(\partial_\nu V^\lambda + \Gamma_{\nu\sigma}^\lambda V^\sigma) - \Gamma_{\mu\nu}^\sigma(\partial_\sigma V^\rho + \Gamma_{\sigma\lambda}^\rho V^\lambda) - (\mu \leftrightarrow \nu) \quad (20)$$

$$\begin{aligned} &= \partial_\mu \partial_\nu V^\rho + (\partial_\mu \Gamma_{\nu\lambda}^\rho) V^\lambda + \Gamma_{\nu\lambda}^\rho \partial_\mu V^\lambda + \Gamma_{\mu\lambda}^\rho \partial_\nu V^\lambda + \Gamma_{\mu\lambda}^\rho \Gamma_{\nu\sigma}^\lambda V^\sigma \\ &\quad - \Gamma_{\mu\nu}^\sigma \partial_\sigma V^\rho - \Gamma_{\mu\nu}^\sigma \Gamma_{\sigma\lambda}^\rho V^\lambda \\ &\quad - \left( \partial_\nu \partial_\mu V^\rho + (\partial_\nu \Gamma_{\mu\lambda}^\rho) V^\lambda + \Gamma_{\mu\lambda}^\rho \partial_\nu V^\lambda + \Gamma_{\nu\lambda}^\rho \partial_\mu V^\lambda + \Gamma_{\nu\lambda}^\rho \Gamma_{\mu\sigma}^\lambda V^\sigma \right. \\ &\quad \left. - \Gamma_{\mu\nu}^\sigma \partial_\sigma V^\rho - \Gamma_{\mu\nu}^\sigma \Gamma_{\sigma\lambda}^\rho V^\lambda \right) \end{aligned} \quad (21)$$

$$= (\partial_\mu \Gamma_{\nu\lambda}^\rho) V^\lambda - (\partial_\nu \Gamma_{\mu\lambda}^\rho) V^\lambda + \Gamma_{\mu\lambda}^\rho \Gamma_{\nu\sigma}^\lambda V^\sigma - \Gamma_{\nu\lambda}^\rho \Gamma_{\mu\sigma}^\lambda V^\sigma \quad (22)$$

$$= \left( \partial_\mu \Gamma_{\nu\lambda}^\rho - \partial_\nu \Gamma_{\mu\lambda}^\rho + \Gamma_{\mu\sigma}^\rho \Gamma_{\nu\lambda}^\sigma - \Gamma_{\nu\sigma}^\rho \Gamma_{\mu\lambda}^\sigma \right) V^\lambda \quad (23)$$

(this derivation is given as in [1]). Thus, we see that

$$[\nabla_\mu, \nabla_\nu]V^\rho = R_{\lambda\mu\nu}^\rho V^\lambda \quad (24)$$

where the Riemann tensor is

$$R_{\lambda\mu\nu}^\rho = \partial_\mu \Gamma_{\nu\lambda}^\rho - \partial_\nu \Gamma_{\mu\lambda}^\rho + \Gamma_{\mu\sigma}^\rho \Gamma_{\nu\lambda}^\sigma - \Gamma_{\nu\sigma}^\rho \Gamma_{\mu\lambda}^\sigma \quad (25)$$

Moreover, it is quite obvious that the Riemann tensor is antisymmetric with respect to the last two indexes.

Notice also that

- If a coordinate system exists in which the components of the metric are constant, then the Riemann tensor vanishes
- If the Riemann tensor vanishes, then we can construct a coordinate system where the metric is constant.

## 4 Contractions of the Riemann tensor

There are two useful contractions of the Riemann tensor:

**the Ricci tensor:**

$$R_{\mu\nu} = R_{\mu\nu\alpha}^\alpha = \partial_\alpha \Gamma_{\mu\nu}^\alpha - \partial_\mu \Gamma_{\alpha\nu}^\alpha + \Gamma_{\alpha\sigma}^\alpha \Gamma_{\mu\nu}^\sigma - \Gamma_{\mu\sigma}^\alpha \Gamma_{\alpha\nu}^\sigma \quad (26)$$

**the Ricci scalar:** this is the trace of the Ricci tensor

$$R = g^{\mu\nu} R_{\mu\nu} = R^\nu_\nu \quad (27)$$

## References

- [1] Sean M Carroll. *Spacetime and geometry*. Cambridge University Press, 2019.